

# Learning summary features of time series for likelihood-free inference



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## 1 CONTEXT

Likelihood-free inference (LFI) methods make **Bayesian inference** on modern physical simulators possible.

Most algorithms use a set of **handcrafted summary features** to describe data.

We propose a **data-driven** approach that learns the most appropriate summary features for LFI on time series data generated by linear and non-linear models

## 2 PROBLEM FORMULATION

We have a simulator parametrized by  $\theta$  that generates time series  $x(t)$

Our goal is to determine an approximation to the posterior distribution of the parameters for a given observed time series:

$$p(\theta|x_o) \approx q_\phi(\theta|f_\lambda(x_o))$$

$\phi$  parametrizes the density estimator  
 $\lambda$  parametrizes the feature extractor

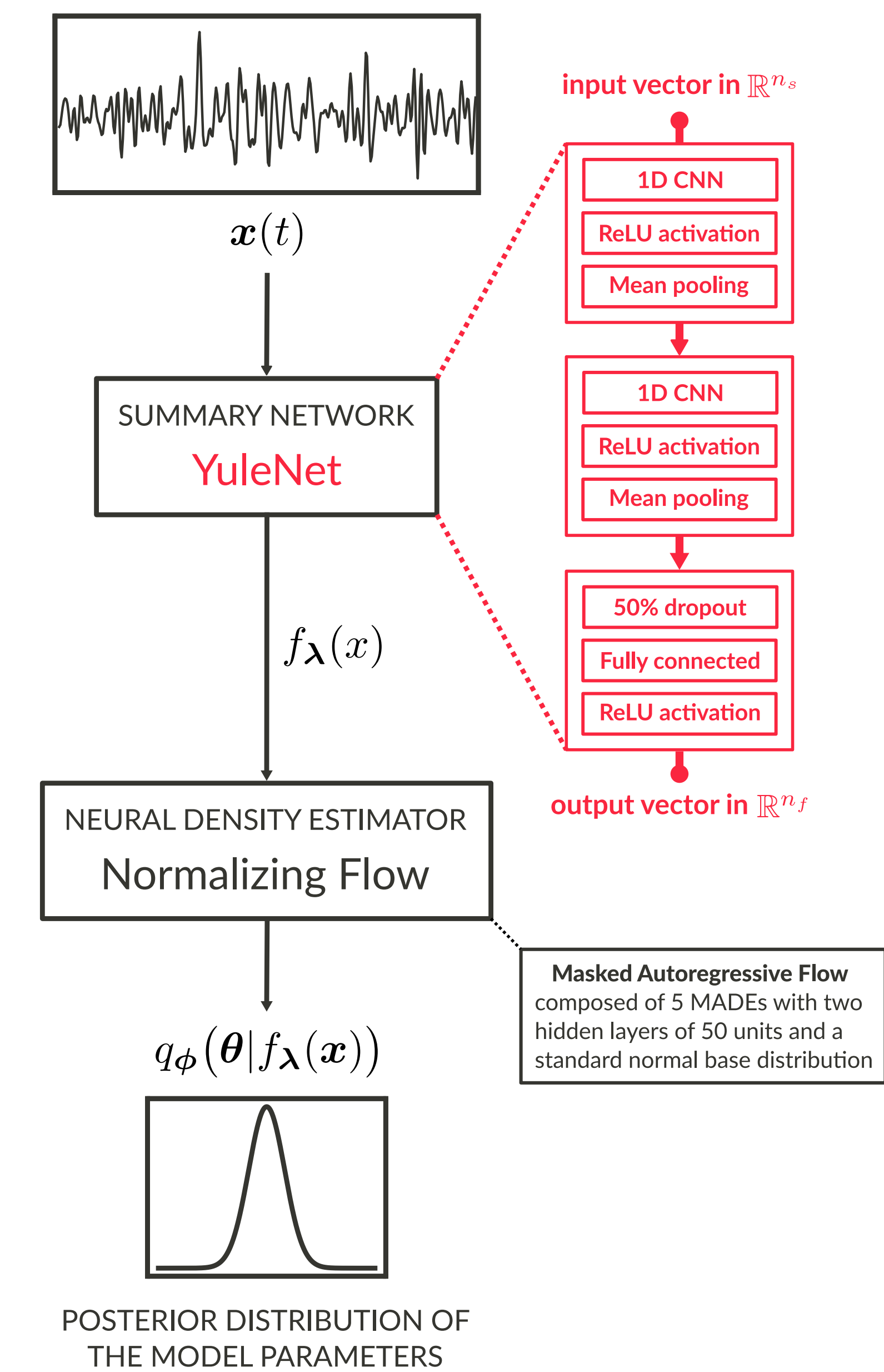
## 3 OUR PROPOSAL

We present the **YuleNet**, a two-layer neural network based on temporal convolutions.

The architecture comes from [1] and has been applied for classifying EEG sleep signals.

We **jointly** estimate  $\phi$  and  $\lambda$  by minimizing  $\mathcal{L}(\phi, \lambda) = \mathbb{E}_{(x, \theta) \sim p(x, \theta)} [-\log(q_\phi(\theta|f_\lambda(x)))]$  with a multiround procedure (SNPE-C) [2].

TIME SERIES GENERATED BY FORWARD MODEL



## 4 NUMERICAL EXPERIMENTS

(1) **Validation** on simulations with linear Gaussian time series models and comparison with inference based on **autocorrelations** as summary features.

Uniformly better results with data driven features than handcrafted ones

(2) **Comparison** of YuleNet to *Partially Exchangeable Networks* (PEN) from [3].

Equivalent results on the Gaussian example but YuleNet has less parameters and demands less computations

(3) Evaluation on a **non-linear** dynamical system and comparison of autocorrelations to YuleNet

Autocorr gives poor results whereas YuleNet finds the ground truth parameters on every situation

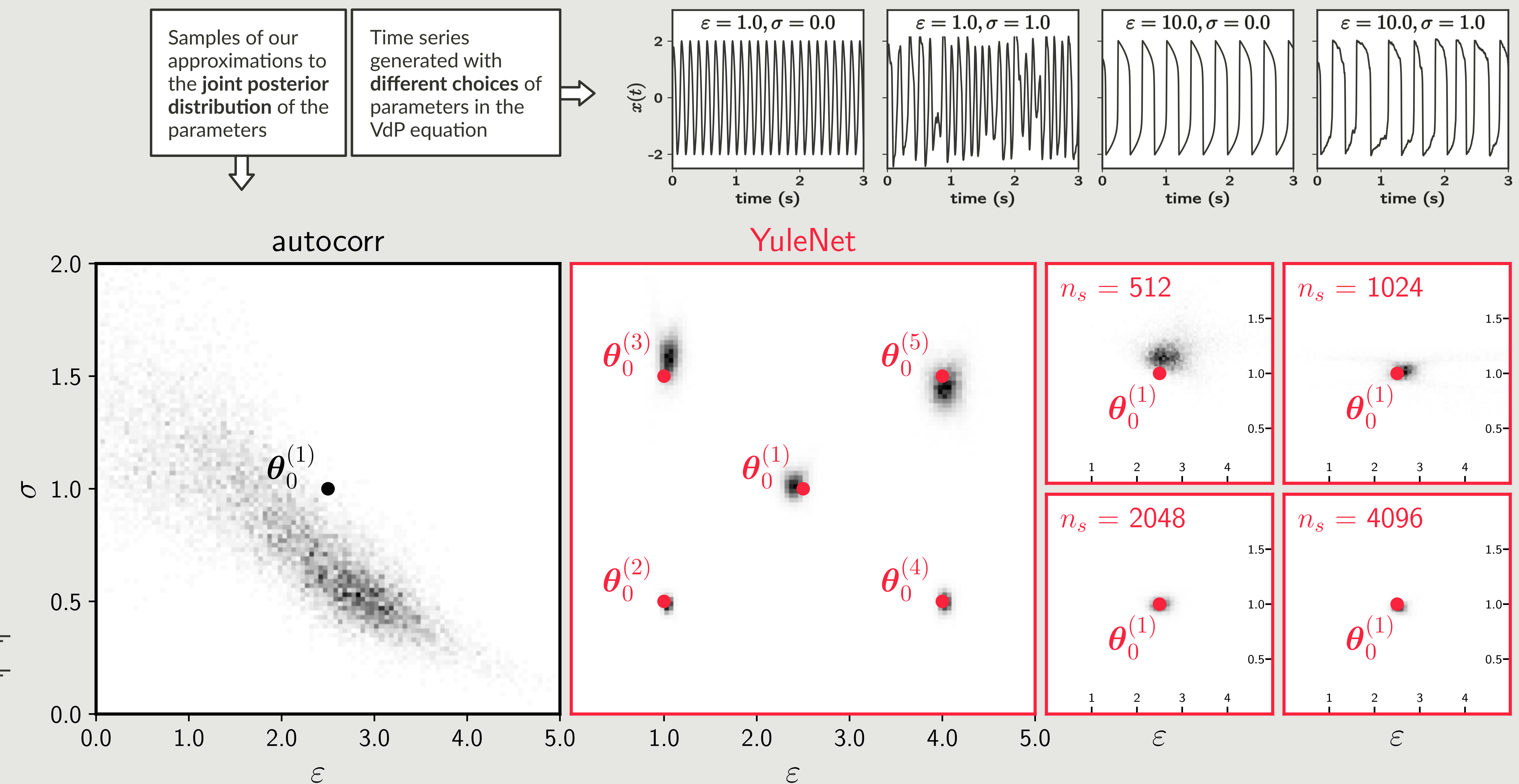
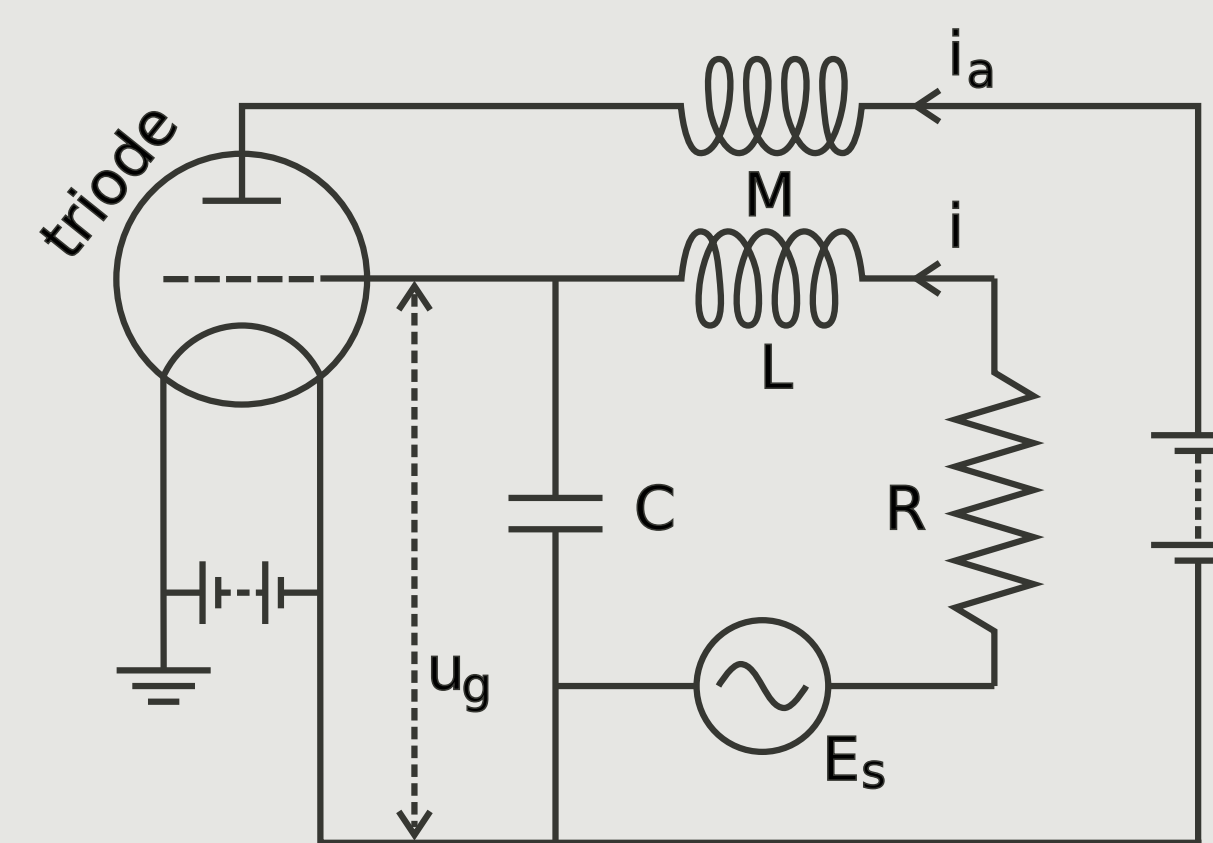
The stochastic Van der Pol Oscillator

$$\ddot{x} = \varepsilon(1 - x^2)\dot{x} - x + \sigma\dot{w}$$

**Observed time series:**  $x(t)$   
 ( $\dot{w}(t)$  is an input Gaussian white noise)

**Parameters to infer:**

- $\sigma$  is the variance of the stochastic input
- $\varepsilon$  is the degree of non-linearity of the VdP model



## 5 DISCUSSION AND CONCLUSION

- YuleNet has good results on **linear** and **non-linear** stochastic models. Better think twice before using **autocorrelations**.
- YuleNet requires **less parameters** to train than PEN and is computationally **efficient**.
- YuleNet is a promising **tool** for studying non-linear dynamical systems such as those used in computational **neuroscience**.

## REFERENCES

- Chambon et al. (2017) - [arxiv.org/abs/1707.03321](https://arxiv.org/abs/1707.03321)
- Greenberg et al. (2019) - [arxiv.org/abs/1905.07488](https://arxiv.org/abs/1905.07488)
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