Dynamical large deviations of kinetically constrained models using neural-network states

Corneel Casert¹, Tom Vieijra¹, Stephen Whitelam², Isaac Tamblyn^{3,4} ¹ Ghent University ² Molecular Foundry, Lawrence Berkeley National Laboratory ³ National Research Council Canada ⁴ Vector Institute for Artificial Intelligence

In brief

- Dynamical large-deviation functions describe the fluctuations of observables measured over stochastic trajectories, and play the role of thermodynamic potentials for trajectories
- They can be found as the largest eigenvalue of a modified version of the Markov generator
- We do so using recurrent neural-network states, and efficiently determine large-deviation functions in two dimensions

The Fredrickson-Andersen model



The FA model describes slow or glassy dynamics by placing kinetic constraints on the dynamics.

It consists of N spins on a lattice which are either up $(n_i = 1)$ or down $(n_i = 0)$, and evolves according to the generator

 $W = \sum_{i} f_i [c(\sigma_i^+ + n_i - 1) + (1 - c)(\sigma_i^- - n_i)],$

where $\sigma_i^+(\sigma_i^-)$ flips a site up (down) and the kinetic constraint $f_i = \sum_{j \in nn(i)} n_j$ is the number of neighboring up-spins.

The dynamical activity K(t), which is the number of configuration changes during a trajectory of time t, can be found through large-deviation theory.

Dynamical activity of the FA model

The distribution of K(t) follows $P(K) \approx e^{-tJ(k)}$, where J(k) is the rate function and $k \equiv K/t$. The cumulants of the dynamical activity can be found through the scaled cumulant-generating function $\theta(s) = \lim_{t\to\infty} \frac{1}{t} \ln \langle e^{-sK} \rangle$. These large-deviation functions are connected through a Legendre transform.

 $\theta(s)$ can be found as the largest eigenvalue of a modified generator, $W^s |P^s\rangle = \theta(s) |P^s\rangle$, where the off-diagonal elements of W^s are multiplied by a factor e^{-s} .

Recurrent neural-network states

We use recurrent neural-network states to solve this eigenproblem variationally. At each site, a recurrent cell receives a previous visible and hidden state from each spatial direction, and calculates a new hidden state and the conditional probability amplitude $\psi(x_i|x_{j < i})$.





The weights of the recurrent cell are variationally optimized in order to find the state with the largest eigenvalue of the modified generator.

This is done for every site, and the total probability amplitude for the configuration is given by $\Psi(\mathbf{x}) = \prod_{i=1}^N \psi(x_i | x_{i-1}, \dots, x_1).$

Results



We uncover a similar phase diagram for the previously unstudied two-dimensional FA model. Large lattices can be studied efficiently by using the RNN cell optimized for a small system as starting point for larger lattices. The derivative of $\theta(s)$ unveils a transition between dynamical phases with low and high activity at a size-dependent value, $s_c \sim N^{-1.07}$

References

Touchette, Hugo. "The large deviation approach to statistical mechanics." Physics Reports 478 (2009)

Hibat-Allah, M., Ganahl, M., Hayward, L. E., Melko, R. G., & Carrasquilla, J "Recurrent neural network wave functions." Physical Review Research 2.2 (2020)

Roth, Christopher. "Iterative Retraining of Quantum Spin Models Using Recurrent Neural Networks." arXiv:2003.06228 (2020).

Bañuls, Mari Carmen, and Juan P. Garrahan. "Using matrix product states to study the dynamical large deviations of kinetically constrained models." Physical Review Letters 123.20 (2019)

Extended version of this work: arXiv:2011.08657

We optimize RNN states for a 1D chain, and can describe the dynamical phase transition between an active and inactive phase, marked by a singularity in $\theta(s)$. Our results are competitive with DMRG.

