Amortized Variational Inference for Type Ia Supernova Light Curves

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Abstract

Markov Chain Monte Carlo (MCMC) methods are widely used for Bayesian inference in astronomy. However, when applied to datasets coming from next-generation telescopes, inference becomes computationally expensive. We propose using amortized variational inference to estimate the posterior of a supernova light curve parametric model. We show that amortization with a recurrent neural network is significantly faster than MCMC while providing competitive estimates of the predictive distribution. To the best of our knowledge, this is the first time this fast amortized framework is applied to supernova light curves. This approach will be essential when estimating the posterior of astrophysical parameters for terabytes of data per night that next-generation telescopes will produce.

1 Introduction

Supernovae (SNe) are highly energetic explosions that occur at the end of the life cycle of stars. These cataclysmic events can be used as extragalactic distance probes and hence are key to further advance cosmological theories [22, 20]. Parametric models are often used to aid the distance determination [10], classification [24], and the physical characterization of SNe [9]. One desired property when performing inference with these models is dealing with the uncertainty present in the data and predictions. Having uncertainties of our estimates is critical for the scientific interpretation of the data, e.g., for the selection of well characterized samples for detailed analysis, for understanding the level of significance of any derived conclusions, or for the reliable identification of extreme or outlier events based on their physical parameters.

Through the use of Bayesian methods we can obtain uncertainty estimates both for the parameters of the model and the predictions obtained by it. However, for complex models the posterior of the parameters may not be analytically tractable. Two possible solutions are the use of Markov Chain

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Figure 1: Amortized variational inference for supernova light curves. The inference networks uses light curves as input, consisting of the time since the first observation t_i , normalized flux f_i and measured error e_i and outputs the variational parameters ϕ for the approximate posterior $q_{\phi}(\theta|x)$. Using samples from this posterior we can sample realizations using the parametric model.

Monte Carlo (MCMC) [18, 5] methods to sample from the posterior and Variational Inference (VI) [15, 4] which optimizes the parameters of an approximate posterior. Both methods present difficulties in scaling to large datasets because applying them for individual light curves is computationally expensive for the entire dataset.

Instead, amortized variational inference (AVI) [17, 21], leverages powerful function approximators, such as deep neural networks, to map the data to the variational parameters directly. This means that after an offline optimization step for the approximator, amortization allows for fast online parameter inference by using the trained approximator. Furthermore, through techniques such as stochastic variational inference (SVI) [12] this approach can scale efficiently to large datasets and even provide inference in batches.

In this paper, we aim at performing fast Bayesian inference on the observed optical flux evolution of astronomical objects, or *light curves*, in preparation for large astronomical surveys such as the Vera C. Rubin Observatory and its Legacy Survey of Space and Time (LSST) [14]. Specifically, we learn a recurrent neural network to perform amortized variational inference over the posterior distribution of a parametric model for supernova light curves. We evaluate our approach on synthetic and real alert light curves from the Zwicky Transient Facility (ZTF) [2], a precursor to the LSST, and compare it against MCMC, both in terms of the estimated posteriors and the computational cost required.

2 Amortized Variational Inference

Consider a parametric model $f(x; \theta)$ where θ represents the set of adjustable parameters. We consider performing fast approximate Bayesian inference for $f(x; \theta)$. Variational Bayesian methods allow us to approximate the posterior of this model by introducing a variational distribution $q_{\phi}(\theta)$ with parameters ϕ . The parameters ϕ are found by maximizing the evidence lower bound (ELBO):

$$ELBO = E_q[\log p(x|\theta)] - D_{KL}(q_\phi(\theta)||p(\theta)), \tag{1}$$

which, when using standard variational inference would require performing optimization for each light curve independently. Instead in AVI we introduce a function g(x) that maps data x to the variational parameters ϕ . This means that instead of learning local parameters for each data point we learn the global parameters of our function g. The introduction of the amortization procedure means we spend an upfront computational cost in learning g(x). However, once this function is learned, performing Bayesian inference is reduced to evaluating this function with new observations to obtain the variational posterior $q_{\phi}(\theta|x)$. For modeling g, neural networks are commonly used, since they are flexible function approximators [7] which are capable of modeling the unknown relationship between data and variational parameters. We apply AVI to infer the parameters of a Sne model from ZTF alert light curves data to the variational parameters ϕ of the approximate posterior. After obtaining $q_{\phi}(\theta|x)$ we sample θ and reconstruct the input using a fixed parameteric SNe model. The inference network is trained by maximizing the ELBO using SVI [12] which enables scaling to larger datasets.

3 Methodology

3.1 Generative model

We consider the widely used parametric model introduced by [1]:

$$f(t) = A \frac{e^{\frac{-(t-t_0)}{\tau_{fall}}}}{1 + e^{\frac{-(t-t_0)}{\tau_{rise}}}},$$
(2)

where $\theta = (A, t_0, \tau_{rise}, \tau_{fall})$ correspond to the parameters of the model. The A parameter is a scaling factor to accommodate the maximum brightness observed. The parameter t_0 corresponds to the time at which the brightness equals A/2. Finally, the parameters τ_{rise} and τ_{fall} represent the rise and fall characteristic timescales of the light curve, respectively. We represent τ_{rise} as a fraction of τ_{fall} with a parameter γ such that $\tau_{rise} = \gamma \tau_{fall}$. All parameters are estimated after the light curve is divided by the maximum flux and time is measured with respect to the time of the first detection.

We assume a normal distribution for the likelihood $p(x|\theta)$, with mean given by Eq. 2 and standard deviation known from the error measurements of the light curves. We assume independent priors based on astronomical knowledge for $p(\theta)$:

$$\begin{aligned} \log(A) &\sim \mathcal{N}(0.397, 0.133) & \log(\gamma) \sim \mathcal{N}(-3, 1) \\ t_0 &\sim \mathcal{N}(0, 10) & \log \tau_{fall} \sim \mathcal{N}(3.47, 0.41) \end{aligned} \tag{3}$$

This parametrization forces the non-negativity of A and τ_{fall} , $0 \le \gamma \le 1$, and allows for t_0 to have negative values (no observations previous to peak). After exponentiating τ_{fall} we add three to constraint its minimum value. Note that we use the same priors on both MCMC and AVI.

3.2 Inference model

For our variational approximation we use a multivariate normal distribution over $\log(A)$, t_0 , $\log(\tau_{fall})$ and $\operatorname{logit}(\gamma)$: $q_{\phi}(\boldsymbol{\theta}|\boldsymbol{x}) = \operatorname{MvN}(\mu, LL^T)$, where $\phi = (\mu, L)$, $\mu \in \mathbb{R}^4$ and L is a 4x4 lower triangular matrix. The parameters ϕ are predicted by the inference network, for which we use a Long Short Term Memory Network (LSTM) [11]. By using a recurrent neural network we can take into account the variable length and irregular sampling of light curves.

3.3 Experimental Setup

We use both real and simulated light curves for our experiments. The real data consists of a set of 709 supernova light curves from the alert stream of ZTF, downloaded using the API of the ALeRCE [8, 23] astronomical broker¹. We use only the 'g' filter and light curves with at least 6 reported alerts and at least 30 days between the first and last observation. The simulated light curves corresponds to a set of 10, 000 simulations based on the priors used and the real data. Both real and simulated light curves are normalized before inference by dividing the fluxes and errors by the maximum flux. We compare our amortized approach with the No U-Turn MCMC sampler (NUTS) [13] from the Stan [6] package. For each light curve in the dataset we run 4 parallel chains for 6, 000 iterations discarding the first 2,000 samples.

The neural network for the amortization is implemented in PyTorch [19] and we use SVI [12] with Pyro [3]. The network is trained for 1,000 epochs using the Adam [16] optimizer with a learning rate of 5×10^{-4} and a batch size of 64, additionally we clip the norm of the gradient to 10. We employ early stopping during our training, where we set the number of epochs with no validation improvement before stopping to 50. Experiments were conducted both on CPU and GPU to measure execution time. The CPU experiments were conducted on a 32 core AMD EPYC processors and the GPU used for the other experiments corresponds to a NVIDIA V100.

¹https://alerceapi.readthedocs.io/en/latest/ztf_db.html

	Synth	etic data	Real data		
	MCMC	Amortized	MCMC	Amortized	
mean	20.92	18.53	-3.05	-31.45	
std	11.42	11.77	150.80	226.63	
5%	9.41	8.12	-74.51	-178.84	
50%	18.26	16.55	16.16	10.92	
95%	41.02	36.99	60.52	42.51	

Table 1: Statistics from the distribution of average log-likelihoods.

Method	Training	Inference	Parar	neter	MCMC	Amortized
MCMC	_	$1,902.74 \pm 183.00$	1	4	0.11	0.14
AVI (CPU)	$1,005.10 \pm 37.35$	29.04 ± 0.84	t	0	1.25	1.73
AVI (GPU)	699.25 ± 29.12	3.79 ± 0.04	$ au_{f} au_{rs}$	all ise	$2.70 \\ 0.98$	$4.05 \\ 1.16$
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Table 2: Time in seconds to perform inference for 10,000 simulated light curves. The reported time corresponds to the mean and standard deviation of 5 runs.

Table 3: Median absolute deviation between the median marginal posterior and the parameter used for the simulation.

4 Results

We evaluate the average log-likelihood for both synthetic and real light curves when the parameters are sampled from the posterior distribution. The distribution of the average likelihood for the data is shown in table 1. We consistently see that the amortized posterior presents lower likelihood than MCMC. However, we can observe that for both synthetic and real data, the median log-likelihood between both approaches remains close.

Table 2 shows the average time required to train the model and infer the parameters in the 10,000 synthetic light curves set using MCMC and AVI. Although training is slower, our approach is ~ 65 times faster when performing inference on CPU and ~ 500 times faster on GPU. Experiments for MCMC are performed using the CPU. This enables the use of approximate inference for future massive surveys, where new alerts arrive on a night by night basis.

For the simulated light curves, we compute the median absolute deviation (MAD) between the known parameter used in the simulation and the median marginal posterior. Table 3 shows that the amortized posterior presents higher MADs compared to MCMC as expected, notably, this error is higher in the t_{fall} parameter, indicating possibly worse fits for the decline of the light curve. This indicates that the decline of the light curves present worse fits than MCMC. On the other hand, for the parameters A and t_0 both approaches exhibit similar errors, with only a difference of 0.5 days for t_0 .

Finally we compare samples from the predictive distribution for real light curves. This is shown in Figure 2, where the top and bottom rows correspond to draws from MCMC and AVI for five selected light curves, respectively. We observe that both methods provide visually similar fits, although AVI predictions are slightly more biased than MCMC. At the same time MCMC provides predictions with higher uncertainties than AVI.

5 Conclusions

With the increase in size of current and future astronomical datasets, classical techniques for Bayesian inference are presented with difficulties in scaling. In this work we used AVI to estimate the posterior of the physical parameters from supernova light curves. The amortized posterior can be obtained significantly faster than MCMC once the inference network is trained, enabling fast Bayesian inference for incoming astronomical surveys like the LSST [14]. As future work we will test this methodology using physical models of other types of transient astronomical objects.



Figure 2: Random samples from the predictive distribution when sampling from the posterior for real data. Top row corresponds to MCMC posterior, bottom row are samples from the amortized posterior. Each example has the log-likelihood shown in the top right corner.

Broader Impact

We believe that the use of amortized inference serves as a first step towards performing Bayesian inference on demand for next generation surveys such as the LSST. For the particular case of Supernovae, having reliable physical parameters and uncertainties will help advance current studies on the physics of these objects and on the large-scale structure in the Universe. The proposed methodology can also benefit studies on other astronomical objects simply by changing the physical model that maps parameters to light curves and the priors.

The posterior distributions obtained using the proposed method can be used as an input to design follow-up rules, i.e. to trigger third-party telescopes to follow novel and/or interesting targets. For the particular case of fast transients follow-up should ideally start as soon as the alerts from the main survey arrive. Quick methods such as the ones proposed in this paper would avoid missing such follow-up targets in the massive streams of near future surveys.

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(a) Do the **claims** made in the abstract and introduction accurately reflect the paper's contributions and scope?

Yes.

- (b) Have you read the ethics review guidelines and ensured that your paper conforms to them? Yes.
- (c) Did you discuss any potential negative societal impacts of your work? No.
- (d) Did you describe the **limitations** of your work? Yes.
- (e) Did you include the code, data, and instructions needed to reproduce the main experimental results (either in the supplemental material or as a URL)? No.
- (f) Did you specify all the training details (e.g., data splits, hyperparameters, how they were chosen)? Yes, the Experimental Setup section details how MCMC was run as well as hyperparameter for the inference network training such as batch size, learning rate, number of epochs, etc.
- (g) Did you report **error bars** (e.g., with respect to the random seed after running experiments multiple times)?

No, only mean and standard deviation is provided for the timing results on Table 2. The rest of the results correspond to a single experiment. However, results in Table 1 show different statistics for the average log-likelihood over the dataset.

- (h) Did you include the amount of compute and the type of resources used (e.g., type of GPUs, internal cluster, or cloud provider)? Yes, a partial description of the hardware used is provided in the Experimental Setup section. Specifically, the number of CPU cores and the GPU model used for experiments.
- (i) If your work uses existing assets, did you cite the creators?
 Yes, we use data from the ALeRCE broker[8] as specified in Experimental Setup and provide a URL.
- (j) Did you mention the license of the assets? No.
- (k) Did you include any new assets either in the supplemental material or as a URL? No.
- Did you discuss whether and how consent was obtained from people whose data you're using/curating? No, the data is publicly available.
- (m) Did you discuss whether the data you are using/curating contains personally identifiable information or offensive content? No.

Appendix

The architecture used for our inference network is shown in Figure 3, we use an LSTM to process the light curve data and then two fully connected networks of two layers each to estimate the parameters of the multivariate normal approximation.



Figure 3: Inference network architecture.